



Experimental and Simulation Studies on Electrothermal Actuators

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Introduction

Microrobotics

- □ Robotics on the micron scale
- □ Utilizes MEMS, MicroAssembly technology
 - Silicon-on-Insulator (SOI) technology too
- Applications in medicine, nanotechnology, and micromanufacturing



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Introduction



Electrothermal Chevron Actuators

- Power microrobots
- Convert electric current to work by Joule effect
 - Electric Current > Heat > Expansion
- This project deals with chevron-powered grippers
 - Design
 - Fabrication
 - Simulation
 - Testing













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Fabrication

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The NSF NNCI Multi-Scale Manufacturing & Nano Intergration Node

□ Fabricated via Silicon-on-Insulator process

- Photolithography
- Deep Reactive Ion Etching
- HF Acid Release

nfrastructure







Experimental Results

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□ Testing:

- Placed probes on contact pads
- Applied DC voltages
 - 20 V to 33.6 V
- Displacements measured by optical metrology
 - Displacement is $\frac{1}{2}$ change in tip gap











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Experimental Results

Over-etching during fabrication

- Prevented characterization of Designs A and C, more time is required to test these
- Design C shows basic functionality





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- □ L-Edit files converted to SolidWorks models, placed in ANSYS
 - Thermal conditions modeled
 - Displacements replicated, temperatures recorded











Conclusions/Future Work



□ Future Work

- Design: redesigning will decrease size, increase usability
- Device Layer Thickness: 20 µm is very thin, 50 or 100 µm would be sturdier
- Fabrication and Testing: more devices could be made and tested, larger sample size

□ Microgrippers were designed and fabricated

- Design B shown to work
 - Voltage: 20 33.6 V
 - Temperature: 43.2 90.2 °C
 - Displacements of 3.8 13.5 µm









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Are there any questions?



